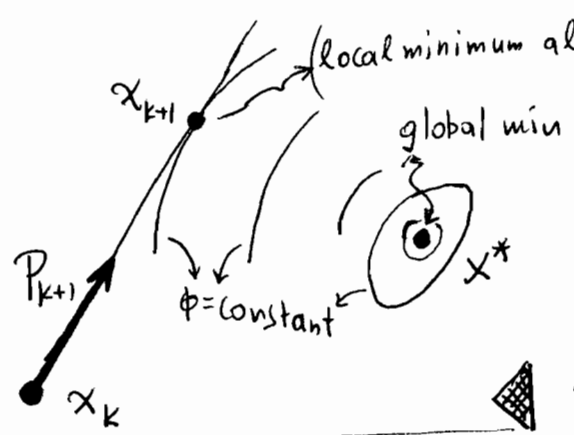


Solving $Ax=b$, A spd, by gradient methods: » Conjugate Gradients «

<1> Solution of $Ax=b$ minimizes $\phi(x) = \frac{1}{2}x^T Ax - x^T b$ (1)

Indeed, if $\bar{x} = x^* + d$ with $Ax^* = b$, A symmetric, positive definite (spd): $\phi(\bar{x}) = \phi(x) + \frac{1}{2}d^T A d \geq \phi(x)$
 since $d^T A d > 0$ if $d \neq 0$ [$= \frac{1}{2}(x^* + d)^T A (x^* + d) - (x^* + d)^T b = \dots$]



<2> Let $x_k \in \mathbb{R}^n$; given direction p_{k+1} , choose α so x_{k+1} is at the minimum of ϕ along that direction.

$$x_{k+1} = x_k + \alpha p_{k+1} \quad ; \quad \alpha = \frac{p_{k+1}^T r_k}{p_{k+1}^T A p_{k+1}} \quad (2)$$

Def: Residual ($r(x) = b - Ax$)
 $r_k = b - Ax_k$

For min: $0 = \frac{\partial \phi}{\partial \alpha} \Big|_{x_{k+1}} =$

$$\begin{aligned} &= \frac{\partial}{\partial \alpha} \left\{ \frac{1}{2} (x_k^T + \alpha p_{k+1}^T) A (x_k + \alpha p_{k+1}) - (x_k + \alpha p_{k+1})^T b \right\} \\ &= \frac{\partial}{\partial \alpha} \left\{ \frac{1}{2} \alpha^2 p_{k+1}^T A p_{k+1} + \alpha (p_{k+1}^T A x_k - p_{k+1}^T b) - x_k^T b \right\} \\ &= p_{k+1}^T \{ \alpha A p_{k+1} - r_k \} = 0 \quad \text{for minimum (2) follows.} \quad (3) \end{aligned}$$

‡ This suggests an algorithm for successive approximation of the solution:

* Step k: (given x_k (approx. solution), p_{k+1} (search direction))

$$\left[\begin{array}{l} r_k = b - Ax_k \quad ; \quad \alpha_{k+1} = p_{k+1}^T r_k / p_{k+1}^T A p_{k+1} \\ x_{k+1} = x_k + \alpha_{k+1} p_{k+1} \quad \text{[New search direction } p_{k+2} \text{?]} \\ \text{How do we choose } p_k \text{?} \end{array} \right.$$

Two basic strategies for choosing P_k :

(i) Steepest descent, (ii) ^{A-}Conjugate directions

(i) Steepest descent: $P_{k+1} := -\nabla\phi|_{x_k} = b - Ax_k = r_k$

Algorithm: given x_0 ; $r_0 = b - Ax_0$
for $k=0, \dots$ $\alpha_{k+1} = r_k^T r_k / r_k^T A r_k$ ($P_{k+1} = r_k$)^{*}

⊛ This choice defines the method. It leads to steepest descent minimization which can be very slow if A is ill-conditioned.

$$x_{k+1} = x_k + \alpha_{k+1} r_k$$

$$r_{k+1} = b - Ax_{k+1} = r_k - \alpha_{k+1} A r_k$$

end

Convergence: Let $AQ = Q\Lambda$,

write $r_k = QS_k$. Then we have $\sum_{i=1}^n (1 - \alpha_{k+1} \eta_i) S_{k,i}^2 = 0$ (4)

$$\blacktriangleleft \alpha_{k+1} = r_k^T r_k / r_k^T A r_k = S_k^T Q^T A Q S_k / S_k^T Q^T A Q S_k = S_k^T S_k / S_k^T \Lambda S_k \blacktriangleright$$

Corollary: $1/\eta_{\max} \leq \alpha_{k+1} \leq 1/\eta_{\min}$ (say $\eta_{\max} = \eta_1$; $\eta_{\min} = \eta_n$). (5)

Substituting r_k in expression for r_{k+1} :

$$QS_{k+1} = r_{k+1} = (I - \alpha_{k+1} A) Q S_k \Rightarrow \underline{S_{k+1} = (I - \alpha_{k+1} \Lambda) S_k} \quad (6)$$

The i -th vector component of the residual, $S_{k,i}$, is multiplied by the factor $(1 - \eta_i \alpha_{k+1})$ to produce $S_{k+1,i}$.

Since (5) $1/\eta_1 \leq \alpha_{k+1} \leq 1/\eta_n$ it follows that $S_{k,1}$ and $S_{k,n}$ have largest negative & positive factors, respectively.

∴ Extreme eigenvector components govern convergence.

(ii) Conjugate directions: choose P_k (linearly independent) so that x_k minimizes $\phi(x)$ in $[P_0, P_1, \dots, P_k]$. If this possible, then will get solution at n -th step (if exact arithmetic).

Thus, want to choose set P_k so that solution to

$$\min_{\alpha} \phi(x_k + \alpha P_{k+1})$$

also gives $\min_{x \in [P_1, \dots, P_k]} \phi(x)$, Now let $x = [P_0, \dots, P_k]$
Then $\Rightarrow x = P_{k+1} y + \alpha P_k$ ($P_{k+1}^{n \times (k+1)}$)

$$\begin{aligned} \phi(x) &= \frac{1}{2} [y^T P_{k+1}^T A P_{k+1} y + \alpha^2 P_k^T A P_k + 2\alpha y^T P_{k+1}^T A P_k] \\ &\quad - y^T P_{k+1}^T b - \alpha P_k^T b \\ &= \phi(P_{k+1} y) + \alpha y^T \{P_{k+1}^T A P_k\} + \underbrace{\frac{\alpha^2}{2} P_k^T A P_k - \alpha P_k^T b}_{\phi(\alpha P_k)} \end{aligned}$$

Hestenes & Stiefel (1952): Let $P_i^T A P_j = 0, i \neq j$. (7)*

Then two separate minimizations!

(i) Let $P_{k+1} y = x_{k+1}$, minimizer over $[P_1, \dots, P_{k+1}]$

(ii) $\alpha = \alpha_k = P_k^T r_{k+1} / P_k^T A P_k$

∴ Must ensure $P_k^T A P_l = 0, k \neq l$; $P_k^T r_{k+1} \neq 0$.

(*) Condition (7) is the A -conjugacy condition that defines the method (still needs a unique specification!)
Since we are building the P_j "from scratch", we need to specify the space they are chosen from. Once that is fixed, the P_j are an A -orthogonal basis. It turns out that $[r_0, \dots, r_{k-1}]$ is a reasonable choice. Then, selecting $P_{k+1} = r_k + \beta P_k$, turns that space into a Krylov space, $\mathcal{K}_n = [r_0, \dots, r_{k-1}]$. Here, why:

Theorem: A spd, $r_k \neq 0$; let $p_0 = 0$. Then

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the recurrence
$$p_{k+1} = r_k + \beta p_k, \quad k \geq 0 \quad (8)$$

with $\beta \equiv \beta_{k+1}$ chosen so that $p_{k+1}^T A p_k = 0$

gives sequences $\{r_0, \dots, r_k, r_{k+1}, \dots\}$, $\{p_0, \dots, p_k, p_{k+1}, \dots\}$
 $\{x_0, \dots, x_k, x_{k+1}, \dots\}$ that satisfy

(i) $p_k \in \mathcal{K}_k$ and $r_k \in \mathcal{K}_{k+1}$

where $\mathcal{K}_k = [r_0, \dots, r_{k-1}]$ is the Krylov space of r_0 .

(ii) $p_{k+1}^T A \zeta = 0, \forall \zeta \in \mathcal{K}_k$ ($p_{k+1} \perp_A \mathcal{K}_k$)

(iii) $r_k^T \zeta = 0, \forall \zeta \in \mathcal{K}_k$ ($r_k \perp \mathcal{K}_k$)

◀ We have the following defining equations for the sequences $\{p_k\}_0^\infty, \{r_k\}_0^\infty$:

$\{p_0 = 0; x_0 \text{ arbitrary}$

$\{r_0 = b - Ax_0$

for $k=0, 1, \dots$: $p_{k+1} = r_k + \beta_{k+1} p_k$; (β_{k+1} chosen to impose $p_{k+1}^T A p_k = 0$)
 $r_{k+1} = r_k - \alpha_{k+1} A p_{k+1}$ $x_{k+1} = x_k + \alpha_{k+1} p_{k+1}$ where
 $\alpha_{k+1} = p_{k+1}^T r_k / p_{k+1}^T A p_{k+1}$

(i) induction assumption: $p_{k-1} \in \mathcal{K}_{k-1}$; $r_k \in \mathcal{K}_{k+1}$; $\mathcal{K}_{k-1} \subset \mathcal{K}_k$

Then $p_{k+1} = r_k + \beta p_k \in \mathcal{K}_{k+1}$ while, since \mathcal{K}_k is the k -th order Krylov space of r_0 , $\mathcal{K}_k \subset \mathcal{K}_{k+1}$ and if

$p_{k+1} \in \mathcal{K}_{k+1} \Rightarrow A p_{k+1} \in \mathcal{K}_{k+2}$ i.e. $r_{k+1} = r_k - \alpha A p_{k+1} \in \mathcal{K}_{k+2}$

(ii) Now the induction assumption is that

(iii)
$$\left. \begin{aligned} p_{\ell-1}^T A \zeta = 0, \forall \zeta \in \mathcal{K}_\ell \\ r_\ell^T \zeta = 0, \forall \zeta \in \mathcal{K}_\ell \end{aligned} \right\} \ell=1, \dots, k-1; \text{ We will show it is true for } \ell=k$$

To show $P_{k+1}^T A \zeta = 0, \zeta \in \mathcal{K}_k$ we can show that
 $P_{k+1}^T A r_l = 0, l=0, \dots, k-1$ (since by assumption the r_l are mutually orthogonal and, so, independent)

Now $P_{k+1}^T A r_l = r_k^T A r_l + \beta_{k+1} P_k^T A r_l$ that is $\mathcal{K}_k = [r_0, \dots, r_{k-1}]$ (9)

(i) For $l \leq k-2: r_l \in \mathcal{K}_{l+1} \subset \mathcal{K}_{k-1}$

But $P_k \perp_A \mathcal{K}_{k-1} = [r_0, \dots, r_{k-2}] \Rightarrow P_k^T A r_l = 0$
 and $r_l \in \mathcal{K}_{k-1} \Rightarrow A r_l \in \mathcal{K}_k \perp r_k \Rightarrow r_k^T (A r_l) = 0$
 $\Rightarrow P_{k+1}^T A r_l = 0, l \leq k-2$

(ii) We may choose β_{k+1} to make $P_{k+1}^T A r_{k-1} = 0$: this gives
 $0 = r_k^T A r_{k-1} + \beta_{k+1} P_k^T A r_{k-1} \Rightarrow \beta_{k+1} = -\frac{r_k^T A r_{k-1}}{P_k^T A r_{k-1}}$ (10)
 (11)

This establishes: $P_{k+1}^T A \zeta = 0, \zeta \in \mathcal{K}_k$


In particular, then: $P_{k+1}^T A P_k = 0$ since $P_k \in \mathcal{K}_k$
 (as well as $P_{k+1}^T A p_l = 0, l=0, \dots, k$)

Similarly, for the residual

$$r_{k+1} = r_k - \alpha_{k+1} A P_{k+1}$$

(a) $r_{k+1}^T r_l = r_k^T r_l - \alpha_{k+1} P_{k+1}^T A r_l; l=0, \dots, k-1$

But $r_k^T r_l = 0$ by assumption
 $P_{k+1}^T A r_l = 0$ by above discussion (11) } $r_{k+1}^T r_l = 0$ (12)

Since $\mathcal{K}_k = \text{span}[r_0, \dots, r_{k-1}]$, see above (9), i.e. $r_{k+1}^T \zeta = 0 \forall \zeta \in \mathcal{K}_k$ 

Efficient Formulation: (minimize computation)

Lemma: $r_k \neq 0$, A spd. Then

$$\alpha_{k+1} = \frac{\|r_k\|_2^2}{\|P_{k+1}\|_A^2} ; \beta_{k+1} = \frac{\|r_k\|_2^2}{\|r_{k-1}\|_2^2}$$

Use: $P_{k+1} = r_k + \beta_{k+1} P_{k-1}$; $r_{k+1} = r_k - \alpha_{k+1} A P_{k+1}$

So: $P_k^T A P_k = P_k^T A (P_{k-1} + \beta_k P_{k-1}) = P_k^T A r_{k-1} = 0$ (13)

$P_k^T r_k = (r_{k-1}^T + \beta_k P_{k-1}^T) r_k = r_{k-1}^T r_k + \beta_k P_{k-1}^T r_k \perp \mathcal{K}_k = 0$ (14)

$P_{k+1}^T r_k = (r_k^T + \beta_{k+1} P_k^T) r_k = r_k^T r_k + \beta_{k+1} P_k^T r_k = \|r_k\|_2^2$ (15)

Then $\alpha_{k+1} = \frac{P_{k+1}^T r_k}{P_{k+1}^T A P_{k+1}} = \frac{\|r_k\|_2^2}{\|P_{k+1}\|_A^2}$ (16)

Also $r_k^T A r_{k-1} = r_k^T A (P_k - \beta_k P_{k-1}) = r_k^T A P_k = P_k^T A r_k$ (17)

(13) $\Rightarrow P_k^T A r_{k-1} = P_k^T A P_k = \|P_k\|_A^2 \stackrel{\text{by (16)}}{=} \|r_{k-1}\|_2^2 / \alpha_k$

(17) $\Rightarrow r_k^T A r_{k-1} = r_k^T A P_k$ } $\Rightarrow r_k^T A r_{k-1} = - \frac{\|r_k\|_2^2}{\alpha_k}$

$\|r_k\|_2^2 = r_k^T (r_{k-1} - \alpha_k A P_k) = -\alpha_k r_k^T A P_k$

So: $\beta_{k+1} = - \frac{r_k^T A r_{k-1}}{P_k^T A r_{k-1}} = \frac{\|r_k\|_2^2}{\|r_{k-1}\|_2^2}$ (18)

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| | |
|----------------------------------------|----------------------------|
| x_0 arbitrary | for $r/w = 1/6 \dots$ |
| $r_0 = b - A x_0$ | $x_1 = x_0 + \alpha_1 P_1$ |
| $P_0 = 0$ | $r_1 = b - A x_1$ |
| $P_1 = r_0$ | β |
| $\alpha_1 = \ r_0\ _2^2 / \ r_0\ _A^2$ | |

for $k=0, 1, \dots$

$\beta_{k+1} = \|r_k\|_2^2 / \|r_{k-1}\|_2^2$

$P_{k+1} = r_k + \beta_{k+1} P_k$

$\alpha_{k+1} = \|r_k\|_2^2 / \|P_{k+1}\|_A^2$

$x_{k+1} = x_k + \alpha_{k+1} P_{k+1}$

$r_{k+1} = r_k - \alpha_{k+1} A P_{k+1}$
or
 $r_{k+1} = b - A x_{k+1}$