

Solutions to HW #6

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$$\textcircled{1} \quad a) \quad L: \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad L(x) = \begin{pmatrix} x_1 + x_2 \\ 3x_2 \end{pmatrix}, \quad x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2$$

L is a linear transformation, because $\forall \alpha, \beta \in \mathbb{R}$ and $x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2, y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \in \mathbb{R}^2$ we have:

$$\begin{aligned} L(\alpha x + \beta y) &= \begin{pmatrix} \alpha x_1 + \beta y_1 + \alpha x_2 + \beta y_2 \\ 3(\alpha x_2 + \beta y_2) \end{pmatrix} \\ &= \begin{pmatrix} \alpha(x_1 + x_2) + \beta(y_1 + y_2) \\ \alpha(3x_2) + \beta(3y_2) \end{pmatrix} \\ &= \alpha \begin{pmatrix} x_1 + x_2 \\ 3x_2 \end{pmatrix} + \beta \begin{pmatrix} y_1 + y_2 \\ 3y_2 \end{pmatrix} = \alpha L(x) + \beta L(y) \end{aligned}$$

$$b) \quad L: \mathbb{R} \rightarrow \mathbb{R}, \quad L(x) = |x|, \quad x \in \mathbb{R}$$

L is not linear because for $x \in \mathbb{R}$ and $y \in \mathbb{R}$:

$$L(x+y) = |x+y| \neq |x| + |y| = L(x) + L(y)$$

$$c) \quad L: \mathcal{P}_2 \rightarrow \mathbb{R}, \quad L(p) = \int_a^b p(x) dx, \quad p \in \mathcal{P}_2$$

L is a linear transformation, because $\forall \alpha, \beta \in \mathbb{R}$ and $p \in \mathcal{P}_2$ and $q \in \mathcal{P}_2$:

$$\begin{aligned} L(\alpha p + \beta q) &= \int_a^b [\alpha p(x) + \beta q(x)] dx \\ &= \int_a^b \alpha p(x) dx + \int_a^b \beta q(x) dx \\ &= \alpha \int_a^b p(x) dx + \beta \int_a^b q(x) dx = \alpha L(p) + \beta L(q). \end{aligned}$$

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② $L: \mathbb{R}^2 \rightarrow \mathbb{R}$, $L(x) = x_1 + x_2$, $\forall x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2$

a) Ker(L)

$$\text{Ker}(L) = \left\{ x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid L(x) = 0 \right\}$$

$$= \left\{ x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid x_1 + x_2 = 0 \right\}$$

$$= \left\{ \begin{pmatrix} x_1 \\ -x_1 \end{pmatrix}, x_1 \in \mathbb{R} \right\}$$

$$= \left\{ \alpha \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \alpha \in \mathbb{R} \right\}$$

$$= \text{span} \left((1, -1)^T \right)$$

b) range(L)

$$\text{range}(L) = \left\{ y \in \mathbb{R} \mid y = L(x), x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \right\}$$

$$= \left\{ y = x_1 + x_2, x_1, x_2 \in \mathbb{R} \right\}$$

$$= \left\{ y = \alpha, \alpha \in \mathbb{R} \right\}$$

$$= \mathbb{R}$$

c) Since $\text{rang}(L) = \mathbb{R}$, the transformation is onto.

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③ $E = \{e_1, e_2, e_3\}$ basis for \mathbb{R}^3

$F = \{b_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, b_2 = \begin{pmatrix} -1 \\ 0 \end{pmatrix}\}$ basis for \mathbb{R}^2

$L: \mathbb{R}^3 \rightarrow \mathbb{R}^2$, $L(x) = (x_1 - x_2)b_1 + (x_1 - x_3)b_2$, $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3$

We need to find $A \in \mathbb{R}^{2 \times 3}$ s.t. $[L(x)]_F = A [x]_E$.

Let $A = [a_1 \ a_2 \ a_3]$.

$a_1 = [L(e_1)]_F$ where $L(e_1) = (1-0)b_1 + (1-0)b_2 = b_1 + b_2$

$\Rightarrow a_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$a_2 = [L(e_2)]_F$ where $L(e_2) = (0-1)b_1 + (0-0)b_2 = -b_1 + 0 \cdot b_2$

$\Rightarrow a_2 = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$

$a_3 = [L(e_3)]_F$ where $L(e_3) = (0-0)b_1 + (0-1)b_2 = 0 \cdot b_1 - b_2$

$\Rightarrow a_3 = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$

Hence, $A = \begin{bmatrix} 1 & -1 & 0 \\ 1 & 0 & -1 \end{bmatrix}$.

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④ $L: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $L(x) = \begin{pmatrix} x_1 + x_2 \\ x_2 + x_3 \\ x_3 + x_1 \end{pmatrix}$, $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3$.

a) Find $A \in \mathbb{R}^{3 \times 3}$ s.t. $[L(x)]_E = A [x]_E$ where $E = \{e_1, e_2, e_3\}$.

Let $A = [a_1 \ a_2 \ a_3]$

$a_1 = [L(e_1)]_E$ where $L(e_1) = \begin{pmatrix} 1+0 \\ 0+0 \\ 0+1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = 1 \times e_1 + 0 \times e_2 + 1 \times e_3$

$\Rightarrow a_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$

$a_2 = [L(e_2)]_E$ where $L(e_2) = \begin{pmatrix} 0+1 \\ 1+0 \\ 0+0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = 1 \times e_1 + 1 \times e_2 + 0 \times e_3$

$\Rightarrow a_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$

$a_3 = [L(e_3)]_E$ where $L(e_3) = \begin{pmatrix} 0+0 \\ 0+1 \\ 1+0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = 0 \times e_1 + 1 \times e_2 + 1 \times e_3$

$\Rightarrow a_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$

Hence, $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$

b) Find $B \in \mathbb{R}^{3 \times 3}$ s.t. $[L(x)]_F = B [x]_F$ where $F = \{u_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, u_2 = \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix}, u_3 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\}$.

Let $B = [b_1 \ b_2 \ b_3]$

$b_1 = [L(u_1)]_F$ where $L(u_1) = \begin{pmatrix} 1+2 \\ 2+3 \\ 3+1 \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ 4 \end{pmatrix}$

to find $\left[\begin{pmatrix} 3 \\ 5 \\ 4 \end{pmatrix} \right]_F$, we need to multiply $\begin{pmatrix} 3 \\ 5 \\ 4 \end{pmatrix}$ by $U^{-1} = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 0 \\ 3 & 0 & 0 \end{bmatrix}^{-1} = \begin{bmatrix} 0 & 0 & 1/3 \\ 0 & 1/2 & -1/3 \\ 1 & -1/2 & 0 \end{bmatrix}$

$\Rightarrow b_1 = \begin{pmatrix} 0 & 0 & 1/3 \\ 0 & 1/2 & -1/3 \\ 1 & -1/2 & 0 \end{pmatrix} \begin{pmatrix} 3 \\ 5 \\ 4 \end{pmatrix} = \begin{pmatrix} 4/3 \\ 7/6 \\ 1/2 \end{pmatrix}$

$$b_2 = [L(u_2)]_F \quad \text{where} \quad L(u_2) = \begin{pmatrix} 1+2 \\ 2+0 \\ 0+1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

$$\Rightarrow b_2 = \begin{pmatrix} 0 & 0 & 1/3 \\ 0 & 1/2 & -1/3 \\ 1 & -1/2 & 0 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 2/3 \\ 2 \end{pmatrix}$$

$$b_3 = [L(u_3)]_F \quad \text{where} \quad L(u_3) = \begin{pmatrix} 1+0 \\ 0+0 \\ 0+1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\Rightarrow b_3 = \begin{pmatrix} 0 & 0 & 1/3 \\ 0 & 1/2 & -1/3 \\ 1 & -1/2 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1/3 \\ -1/3 \\ 1 \end{pmatrix}$$

Hence,
$$B = \begin{bmatrix} 4/3 & 1/3 & 1/3 \\ 7/6 & 2/3 & -1/3 \\ 1/2 & 2 & 1 \end{bmatrix}$$

c) S : transition matrix to change basis from F to E :

given $x = \alpha u_1 + \beta u_2 + \gamma u_3$, find $x = a e_1 + b e_2 + c e_3$

This means
$$\underbrace{[u_1 \ u_2 \ u_3]}_S \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} = \underbrace{[e_1 \ e_2 \ e_3]}_I \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix} = S \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} \quad \text{where} \quad S = [u_1 \ u_2 \ u_3] = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 0 \\ 3 & 0 & 0 \end{bmatrix}$$

We finally verify that $SB = AS$:

$$SB = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 0 \\ 3 & 0 & 0 \end{pmatrix} \begin{pmatrix} 4/3 & 1/3 & 1/3 \\ 7/6 & 2/3 & -1/3 \\ 1/2 & 2 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 3 & 1 \\ 5 & 2 & 0 \\ 4 & 1 & 1 \end{pmatrix}$$

$$\Rightarrow SB = AS \Rightarrow B = S^{-1}AS.$$

$$AS = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 0 \\ 3 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 3 & 3 & 1 \\ 5 & 2 & 0 \\ 4 & 1 & 1 \end{pmatrix}$$