Inverse vs Implicit function theorems - MATH 402/502 - Spring 2015  
April 24, 2015

Instructor: C. Pereyra

Prof. Blair stated and proved the Inverse Function Theorem for you on Tuesday April 21st. On Thursday April 23rd, my task was to state the Implicit Function Theorem and deduce it from the Inverse Function Theorem. I left my notes at home precisely when I needed them most. This note will complement my lecture.

As it turns out these two theorems are equivalent in the sense that one could have chosen to prove the Implicit Function Theorem and deduce the Inverse Function Theorem from it. I showed you how to do that and I gave you some ideas how to do it the other way around.

**Inverse Function Theorem**

The inverse function theorem gives conditions on a differentiable function so that locally near a base point we can guarantee the existence of an inverse function that is differentiable at the image of the base point, furthermore we have a formula for this derivative: the derivative of the function at the image of the base point is the reciprocal of the derivative of the function at the base point. (See Tao’s Section 6.7.)

**Theorem 0.1 (Inverse Function Theorem).** Let $E$ be an open subset of $\mathbb{R}^n$, and let $f : E \to \mathbb{R}^n$ be a continuously differentiable function on $E$. Assume $x_0 \in E$ (the base point) and $f'(x_0) : \mathbb{R}^n \to \mathbb{R}^n$ is invertible. Then there exists an open set $U \subset E$ containing $x_0$, and an open set $V \subset \mathbb{R}^n$ containing $f(x_0)$ (the image of the base point), such that $f$ is a bijection from $U$ to $V$. In particular there is an inverse map $f^{-1} : V \to U$. Moreover $f^{-1}$ is differentiable at $y_0$ and

$$ (f^{-1})'(y_0) = (f'(x_0))^{-1}. \quad (0.1) $$

When $n = 1$ this is the familiar one-variable inverse function theorem (Theorem 10.4.2) that we discussed in Math 401.

**Heuristics:** To understand where formula (0.1) comes from, it is illuminating to consider the linear approximation $y$ in $\mathbb{R}^n$ to $f(x)$ near the base point $x_0$

$$ y = y_0 + f'(x_0)(x - x_0). $$

We can solve for $x$ in terms of $y$ provided $f'(x_0)$ is invertible, which is our driving hypothesis,

$$ x = x_0 + (f'(x_0))^{-1}(y - y_0). $$

This time we expect $x$ to be a linear approximation to $f^{-1}(y)$ near $y_0$, in which case we will conclude that $(f^{-1})'(y_0) = (f'(x_0))^{-1}$, the formula in the theorem.

1. **Implicit Function Theorem**

The implicit function theorem gives sufficient conditions on a function $F$ so that the equation $F(x, y) = 0$ can be solved for $y$ in terms of $x$ (or solve for $x$ in terms of $y$) locally near a base point $(x_0, y_0)$ that satisfies the same equation $F(x_0, y_0) = 0$.

Here is the version of the theorem I stated in class on Thursday, it is designed to be able to deduce the inverse function theorem from it.
Theorem 1.1 (Implicit Function Theorem I). Let $m, n$ be positive integers. Let $A$ be an open subset of $\mathbb{R}^{n+m}$, and let $F : A \rightarrow \mathbb{R}^m$ be a continuously differentiable function on $A$. Let $(x_0, y_0) \in A$ such that $F(x_0, y_0) = 0$. Assume that $D_Y F(x_0, y_0)$ is invertible. Then there are open sets $U \subset \mathbb{R}^n$ and $V \subset \mathbb{R}^m$ such that $x_0 \in U$, $y_0 \in V$, and there is a function $g : U \rightarrow V$ differentiable at $x_0$ such that $(x, g(x)) \in A$ and $F(x, g(x)) = 0$ for all $x \in U$. Moreover
\begin{equation}
(1.1) \quad g'(x) = -(D_Y F(x_0, y_0))^{-1}D_X F(x_0, y_0).
\end{equation}

Heuristics: To understand where formula (1.1) comes from, it is illuminating to use a linear approximation $z$ in $\mathbb{R}^m$ to $F(x, y)$ near the base point $(x_0, y_0)$ with $z_0 = F(x_0, y_0) = 0$,
\[ z = z_0 + F'(x_0, y_0)(x - x_0, y - y_0). \]
Remember we are solving the equation $z = F(x, y) = 0$ so this becomes
\[ 0 = [D_X F(x_0, y_0), D_Y F(x_0, y_0)](x-x_0, y-y_0)^t = D_X F(x_0, y_0)(x-x_0) + D_Y F(x_0, y_0)(y-y_0). \]
We can solve the linear equation for $y$ in terms of $x$ provided $D_Y F(x_0, y_0)$ is invertible which is the assumption to get,
\[ y = y_0 - (D_Y F(x_0, y_0))^{-1}D_X F(x_0, y_0)(x - x_0). \]
We expect $y$ to be a linear approximation to $g(x)$ for $x$ near $x_0$, and hence $g'(x) = -(D_Y F(x_0, y_0))^{-1}D_X F(x_0, y_0)$ as expected.

Proof of Inverse Function Theorem given Implicit Function Theorem I. We are given $f : E \rightarrow \mathbb{R}^n$ a continuously differentiable function on the open $E \subset \mathbb{R}^n$, $x_0 \in E$ (the base point), let $y_0 = f(x_0)$, and we are given that $f'(x_0) : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is invertible. Let us define $F : A \rightarrow \mathbb{R}^n$ where $A = E \times \mathbb{R}^n \subset \mathbb{R}^{n+m} = \mathbb{R}^{2n}$ by
\[ F(x, y) = y - f(x), \quad F(x_0, y_0) = 0 \]
We wish to apply the implicit function theorem to this function but we want to write $x$ in terms of $y$, so we must verify that $D_X F(x_0, y_0)$ is invertible. A calculation shows that
\[ F'(x_0, y_0) = [-f'(x_0), I_{n \times n}], \]
where $I_{n \times n}$ is the $n \times n$ identity matrix. Hence $D_X F(x_0, y_0) = -f'(x_0)$, and is invertible by assumption on $f$, and $D_Y F(x_0, y_0) = I_{n \times n}$. We can apply the theorem, there are open sets $U \subset \mathbb{R}^n$ and $V \subset \mathbb{R}^n$ such that $x_0 \in U$, $y_0 \in V$ and a function $g : V \rightarrow U$ differentiable at $y_0$ such that $(g(y), y) \in A$ and $F(g(y), y) = 0$ for all $y \in V$. Moreover $g$ is differentiable at $y_0$ and $g'(y_0) = -(D_X F(x_0, y_0))^{-1}D_Y F(x_0, y_0) = (f'(x_0))^{-1}$. Notice that because of our choice of function $F$, $0 = F(g(y), y) = y - f(g(y))$, that is we conclude that $y = f(g(y))$ for all $y \in V$, that is $g = f^{-1}$ on $V$ and
\[ (f^{-1})'(y_0) = -( -f'(x_0))^{-1}I_{n \times n} = (f'(x_0))^{-1}. \]
\[ \square \]
\[ ^1 \text{Note that } F'(x_0, y_0) = [D_X F(x_0, y_0), D_Y F(x_0, y_0)], D_X F(x_0, y_0) \text{ is an } m \times n \text{ matrix, and } D_Y F(x_0, y_0) \text{ is an } m \times m \text{ matrix.} \]
2. Inverse implies Implicit

We will deduce a second statement for the implicit function theorem as a corollary of the inverse function theorem.

**Theorem 2.1 (Implicit Function Theorem II).** Let \( m, n \) be positive integers. Let \( E \) be an open subset of \( \mathbb{R}^{n+m} \), and let \( F : E \to \mathbb{R}^m \) be a continuously differentiable function on \( E \). Let \((x_0, y_0) \in E\) such that \( F(x_0, y_0) = 0 \). Assume that \( D_Y F(x_0, y_0) \) is invertible\(^2\). Then there are open sets \( W \subset \mathbb{R}^n \) and \( V \subset E \subset \mathbb{R}^{n+m} \) such that \( x_0 \in W \), \((x_0, y_0) \in V\), and there is a function \( G : W \to \mathbb{R}^m \) differentiable at \( x_0 \) such that
\[
\{(x, y) \in V : F(x, y) = 0\} = \{(x, G(x)) : x \in W\}.
\]
Moreover
\[
G'(x_0) = -\left( D_Y F(x_0, y_0) \right)^{-1} D_X F(x_0, y_0).
\]

**Proof of Implicit Function Theorem given Inverse Function Theorem.** We are given a continuously differentiable function \( F : E \to \mathbb{R}^m \), \( E \) open subset of \( \mathbb{R}^{n+m} \), \((x_0, y_0) \in E\) such that \( F(x_0, y_0) = 0 \), and we are given that \( D_Y F(x_0, y_0) \) is invertible. Define a new continuously differentiable function \( f : E \to \mathbb{R}^{n+m} \) by
\[
f(x, y) := (x, F(x, y)),
\]
to which we want to apply the inverse function theorem at the base point \( z_0 = (x_0, y_0) \), and at its image point under \( f \), \( f(z_0) = (x_0, F(x_0, y_0)) = (x_0, 0) \). We must first verify that \( f'(z_0) \) is invertible. The \((n+m) \times (n+m)\) matrix representation of the linear transformation \( f'(z_0) \) is given by the following block matrix
\[
f'(z_0) = \begin{bmatrix}
I_{n \times n} & 0_{n \times m} \\
D_X F(x_0, y_0) & D_Y F(x_0, y_0)
\end{bmatrix},
\]
where \( I_{n \times n} \) is the \( n \times n \) identity matrix and \( 0_{n \times m} \) is the \( n \times m \) zero matrix. One can operate with block matrices like if we had a \( 2 \times 2 \) lower triangular matrix with no zeros in the diagonal\(^3\) and verify that
\[
(f'(z_0))^{-1} = \begin{bmatrix}
I_{n \times n} & 0_{n \times m} \\
-(D_Y F(x_0, y_0))^{-1} D_X F(x_0, y_0) & (D_Y F(x_0, y_0))^{-1}
\end{bmatrix}
\]
So \( f'(z_0) \) is invertible and the inverse function theorem ensures that there exists an open set \( U \subset E \subset \mathbb{R}^{n+m} \) containing \( z_0 \), and an open set \( V \subset \mathbb{R}^{n+m} \) containing \( f(z_0) \).

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\(^2\)Note that \( F'(x_0, y_0) = [D_X F(x_0, y_0), D_Y F(x_0, y_0)] \) and \( D_X F(x_0, y_0) \) is an \( m \times n \) matrix, \( D_Y F(x_0, y_0) \) is an \( m \times m \) matrix.

\(^3\)In this case \( 1 \neq 0 \) and \( c \neq 0 \): \( A = \begin{bmatrix} 1 & 0 \\ b & c \end{bmatrix} \), \( A^{-1} = \begin{bmatrix} 1 & 0 \\ -c^{-1}b & c^{-1} \end{bmatrix} \).
(the image of the base point), such that \( f \) is a bijection from \( U \) to \( V \). In particular there is an inverse map \( f^{-1} : V \to U \). Moreover \( f^{-1} \) is differentiable at \( f(z_0) \) and
\[
(f^{-1})'(f(z_0)) = (f^{-1})'(x_0, 0) = (f'(x_0, y_0))^{-1}.
\]

Let us write \( f^{-1} \) in coordinates, \( f^{-1} = (h, g) \) where \( h = (h_1, h_2, \ldots, h_m) \) and \( g = (g_1, g_2, \ldots, g_m) \), and \( h_i, g_i : V \to \mathbb{R} \). Since \( (h(x, y), F(h(x, y), g(x, y))) = f(f^{-1}(x, y)) = (x, y) \) then \( h_i(x, y) = x_i \) for all \( i = 1, 2, \ldots, n \), and \( F(h(x, y), g(x, y)) = F(x, g(x, y)) = y. \) Also \( g \) is differentiable at \((x_0, 0) \in U\). We now define \( W \subset \mathbb{R}^n \) and function \( G : W \to \mathbb{R}^m \) as follows
\[
W := \{ x \in \mathbb{R}^n : (x, 0) \in U \}, \quad G(x) := g(x, 0) \quad \text{for} \quad x \in W.
\]

Note that \( x_0 \in W \), and since \( U \) is open in \( \mathbb{R}^{n+m} \), \( W \) which is the projection of \( U \) onto \( \mathbb{R}^n \) is also open in \( \mathbb{R}^n \), finally \( G \) so defined is differentiable at \( x_0 \). We now prove (??), namely
\[
A := \{ (x, y) \in V : F(x, y) = 0 \} = \{ (x, G(x)) : x \in W \} =: B.
\]

Assume \((x, y) \in V \) and \( F(x, y) = 0 \) then \( f(x, y) = (x, 0) \in U \) therefore \( x \in W \). Applying \( f^{-1} \), we see that \((x, y) = f^{-1}(x, 0) \) in particular \( y = g(x, 0) = G(x) \), therefore \( A \subset B \). All the steps can be reversed since \( f \) is a bijection from \( U \) to \( V \) to obtain the other set inequality.

By previous discussion \( F(x, G(x)) = 0 \) for all \( x \in W \), \( F \) is differentiable at \((x_0, G(x_0)) = (x_0, y_0) \) and \( G \) is differentiable at \( x_0 \), the formula for the derivative follows by the chain rule:
\[
D_X F(x_0, y_0) + D_Y F(x_0, y_0) G'(x_0) = 0,
\]
and by simple algebra we conclude that \( G'(x_0) = -\left(D_Y F(x_0, y_0)\right)^{-1} D_X F(x_0, y_0). \)

\[\square\]

**Remark 2.2.** Tao only proves the implicit function theorem when \( m = 1 \), but basically is the same argument I just presented, see Section 6.8 in Book II. With only the case \( m = 1 \) he couldn’t go from implicit to inverse function theorem except in the case \( n = m = 1 \), because one needs the implicit function theorem from \( \mathbb{R}^{2n} \) into \( \mathbb{R}^n \), that is the case \( n = m \).

**Remark 2.3.** Final comment, under the hypothesis that the functions are continuously differentiable one gets more differentiability than just at the base point, because the hypothesis of invertibility of the matrices \( f'(x_0) \) or \( D_Y F(x_0, y_0) \) will persist in a neighborhood of \( x_0 \) or \((x_0, y_0) \) respectively. The Theorems can be strenghtened to say that \( f^{-1} \) is continuously differentiable on a possibly smaller open set \( V \), and \( G \) is continuously differentiable on a possibly smaller open set \( W \).