

Math. 375, Fall 2005
2. Matrices and Vectors

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$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}$$



Square matrix: size $n \times n$

$$A = [1, 2, 3; 4, 5, 6];$$

Rectangular matrix,
size 2×3

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

Concepts from Linear Algebra

- Eigenvalues and Eigenvectors

$$\mathbf{eig}(A)$$

- Solution of Linear Systems

$$\mathbf{x} = A/b$$

- Linear Independence

- Determinants

$$\mathbf{d} = \det(A)$$

- Matrix Inverse

$$\mathbf{B} = \mathbf{inv}(A)$$

Special Matrices and Commands

- Identity: $E = \text{eye}(n)$
- Zero matrix: $\text{zeros}(m,n)$
- Inverse: $\text{inv}(A)$
- Matrix sum: $A+B$ (both must be $m \times n$)
- Matrix product: $C = A*B$
(A is $m \times k$, B is $k \times n$ and C is $m \times n$)
- Dimensions: $\text{size}(A) = (m,n)$
- Determinant: $\text{det}(A)$

```
% Banded Matrices
```

```
% script tridiag
```

```
A=[ 0  1  2  3;  
    -1 0  1  2;  
    -2 -1 0  1;..  
    -3 -2 -1 0;  
    -4 -3 -2 -1];
```

```
v=diag(A,-1)
```

```
C=diag(v,3)
```

```
B1 = tril(A,1)
```

```
B2 = triu(A,-1)
```

```
T1 =-triu(tril(ones(6,6),1),-1)+3*eye(6,6)
```

```
T2 =-diag(ones(5,1),-1)+diag(ones(6,1),0)...  
    -diag(ones(5,1),1)
```

```
T3 = toeplitz([2;-1;zeros(4,1)])
```

Matrix displays

- `spy(A)`
- `image(A)`
- `mesh(A)`
- `pltmat(A,'name',colormap,font)`
- `load gatlin, image(X);colormap(map),...`
- `bar3(A)`
- `>>demo: graphs & matrices, intro`
- `whos` shows workspace

Arrays: vectors

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$\vec{x}' = [x_1 \quad x_2 \quad x_3 \quad x_4]$$

\mathbf{x} is a **column** vector while its transpose, \mathbf{x}' , is a **row** vector

Basic vector/matrix operations

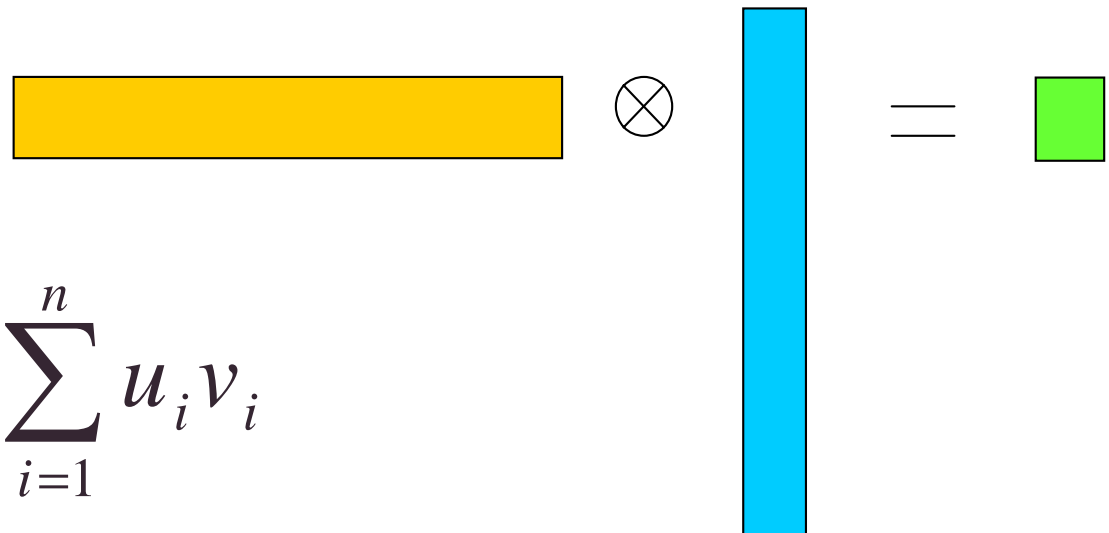
Inner product: $\mathbf{u}' * \mathbf{v} = \text{dot}(\mathbf{u}, \mathbf{v})$;

sum=0;

for i=1:length(u)

 sum = sum+u(i)*v(i);

end



$$\langle \mathbf{u}, \mathbf{v} \rangle = \mathbf{u}' \mathbf{v} = \sum_{i=1}^n u_i v_i$$

Outer Product: $u \cdot v'$;

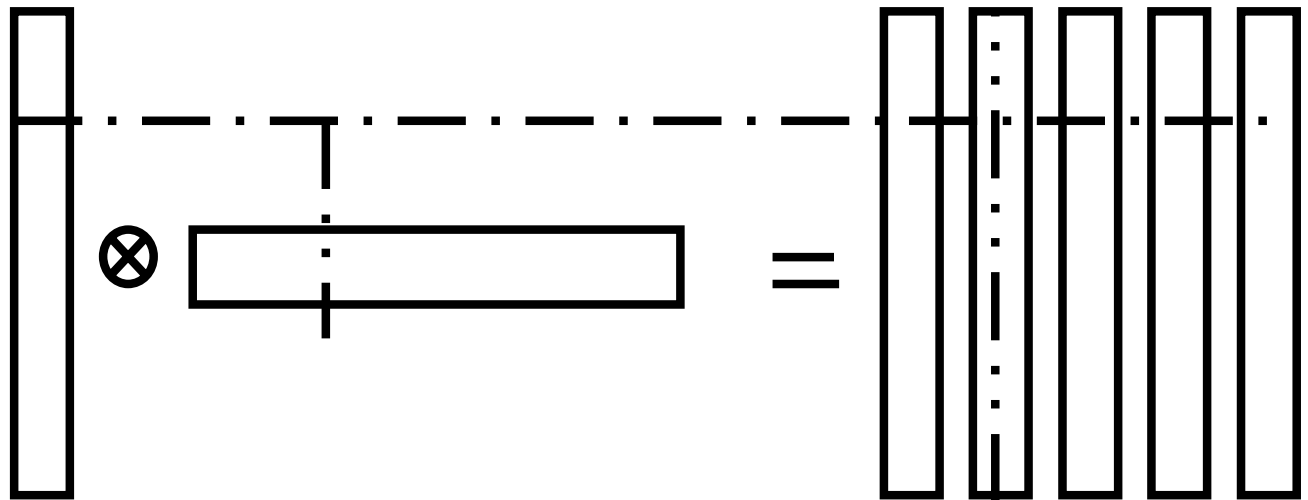
for $i=1:\text{length}(u)$

for $j=1:\text{length}(v)$

$uv(i,j) = u(i) \cdot v(j)$;

end

end



$$u \otimes v = uv' = (u_i v_j)$$

Pointwise operations

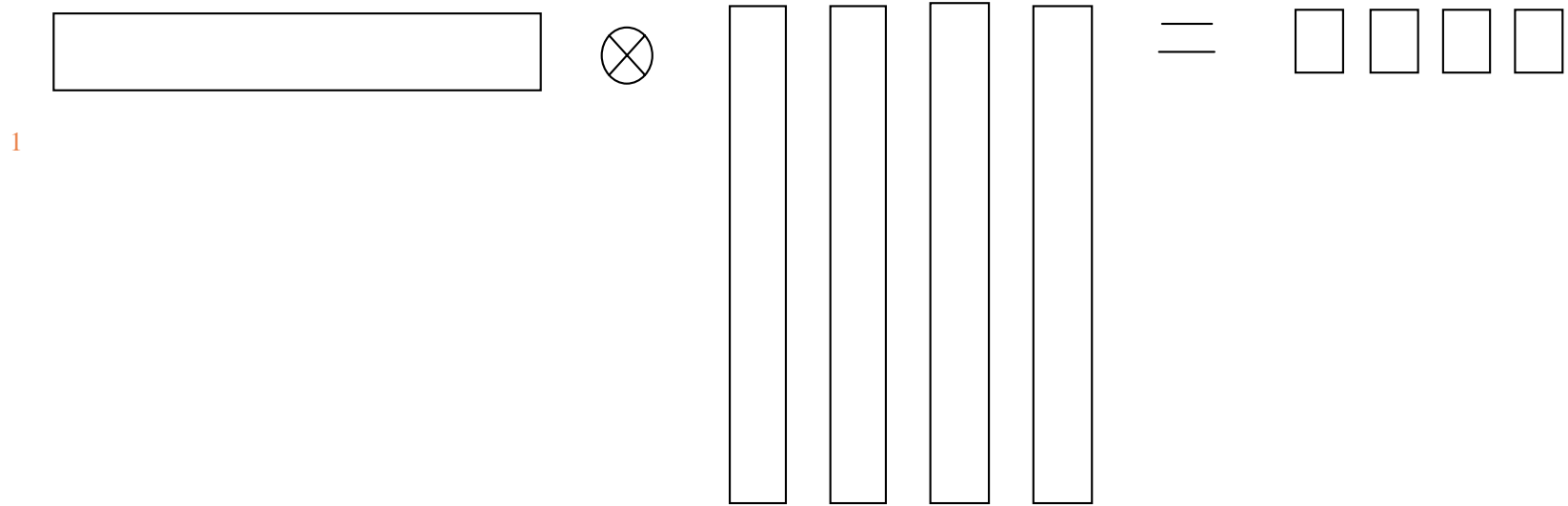
$$x = [x_1 \quad x_2 \quad x_3]$$

$$y = [y_1 \quad y_2 \quad y_3]$$

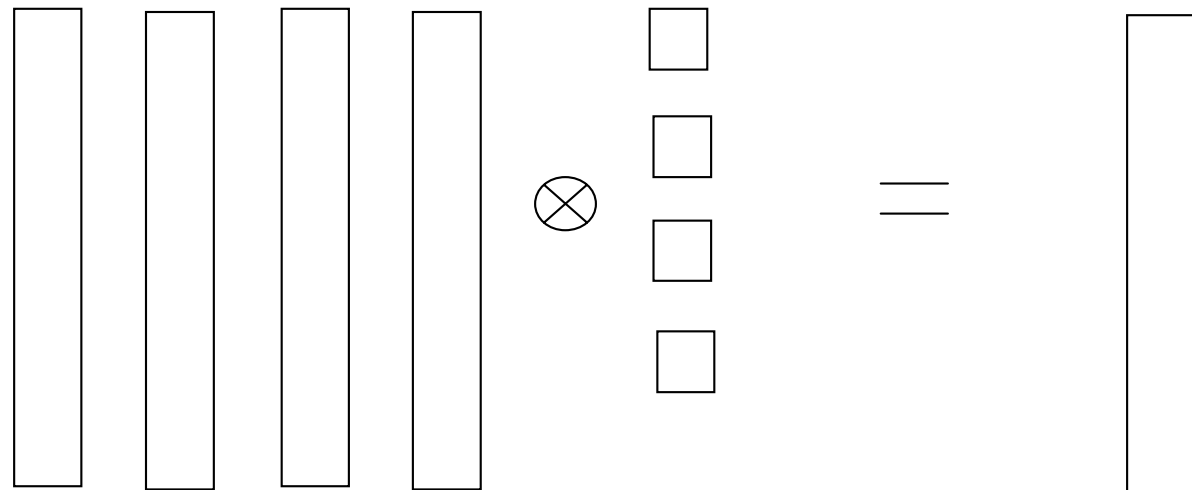
$$x.*y = [x_1y_1 \quad x_2y_2 \quad x_3y_3]$$

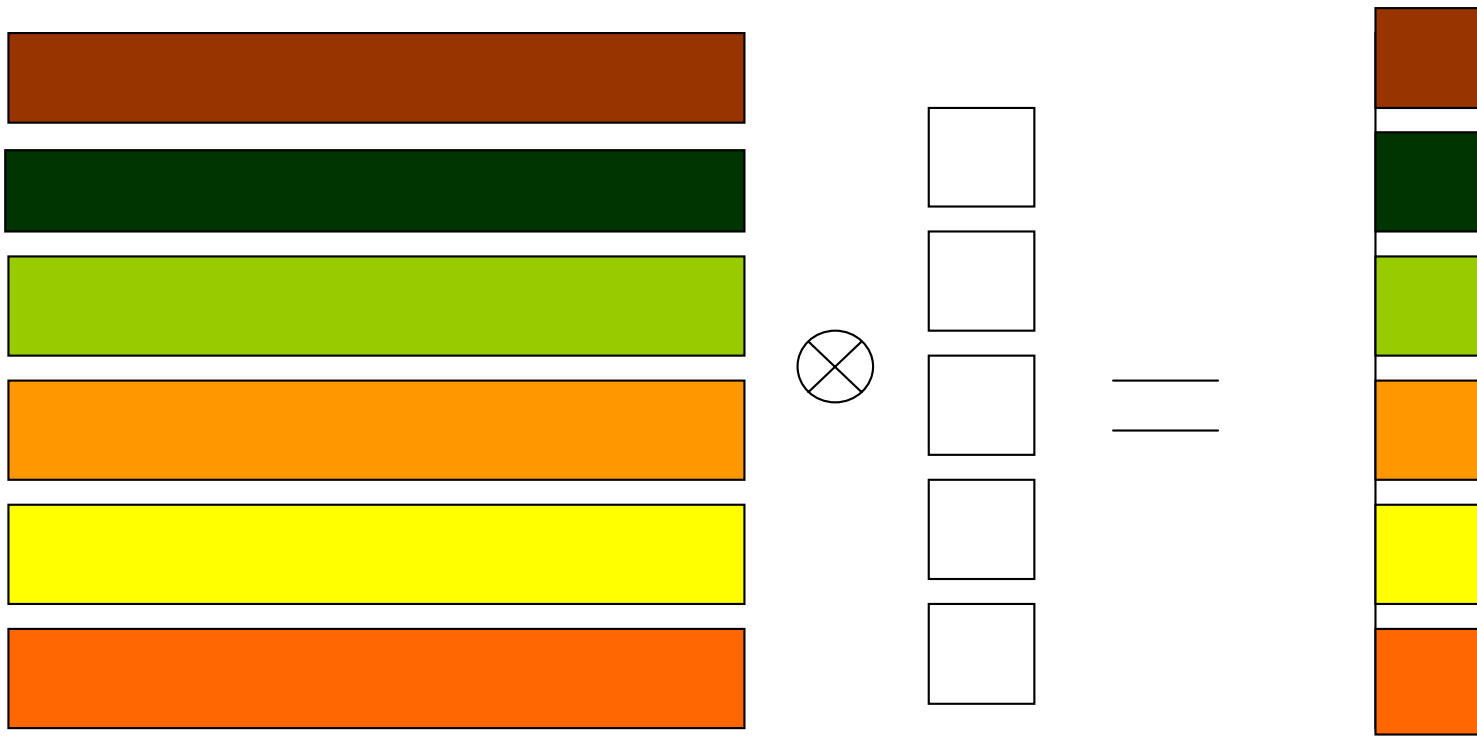
$$x.^2 = [x_1^2 \quad x_2^2 \quad x_3^2]$$

1xN row \times Nx4 matrix = 1x4 row



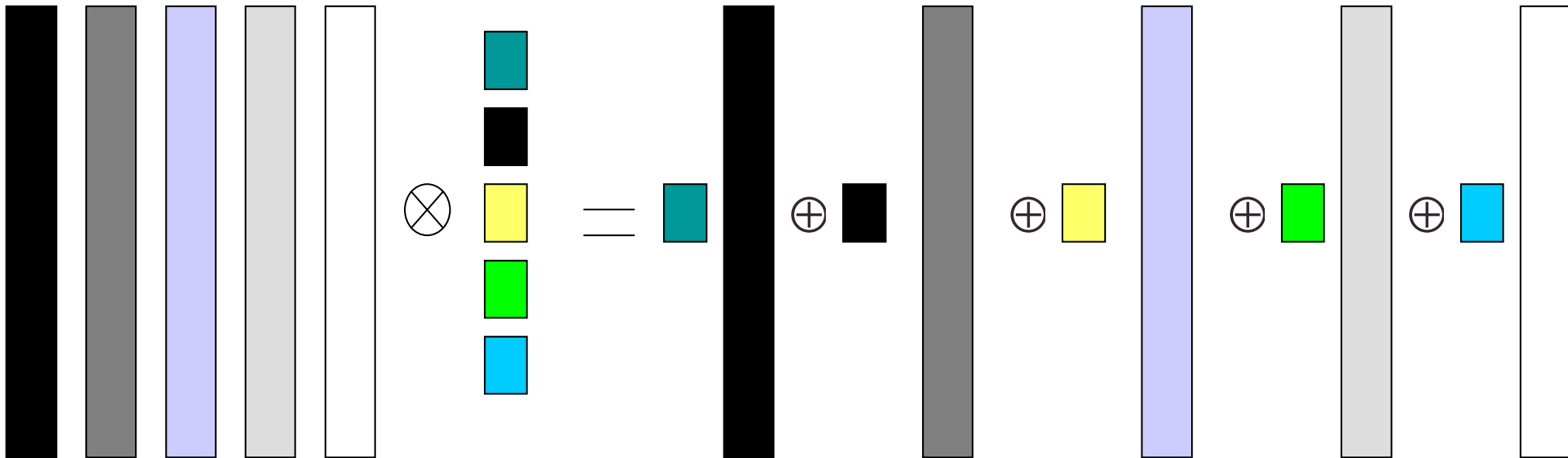
Nx4 matrix \times 4x1 column = Nx1 column





Matrix-Vector multiplication:
 The **ROW** picture

Matrix-Vector Multiplication: The **COLUMN** picture



II. VECTOR OPERATIONS:

(1) vector: scale, add, subtract

(scalar*vector):

$$2*[10 \ 20 \ 30] = [20 \ 40 \ 60]$$

(2) POINTWISE vector:

multiply, divide, exponentiate

(pointwise vector * vector):

$$[2 \ 3 \ 4].*[10 \ 20 \ 30] = [20 \ 60 \ 120]$$

(for pointwise operations,
dimensions must be identical!)

(3) Vector linear combos: matrix*vector, $A*x$

(4) `size(A)` gives array dimensions

(array, can be used to index other arrays)

`length(x)` gives vector dimension

(5) `for k = 1:n`

(operations)

`end`

(loop around n times)